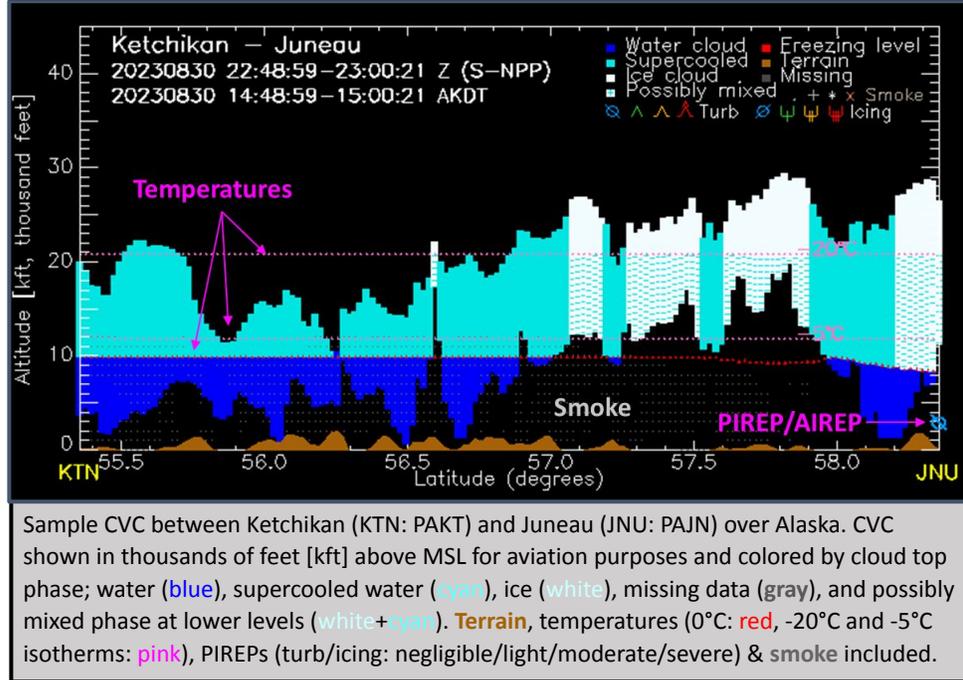


What is the cloud cross section product?

This **experimental** product is part of a 3D, satellite-based cloud height field that displays where clouds are present in a vertical column of the atmosphere. Information on 3D cloud structure is important for the aviation community. The cloud cross section is computed along flight routes from cloud products derived from operational NOAA satellites, including **Cloud Top Height (CTH)** and **Cloud Base Height (CBH)**, and is supplemented with additional data useful for aviation (e.g., temperature, **PIREPs**, and the presence of smoke). These data sets are interpolated to a common grid in order to provide cloud vertical structure information along flight paths.



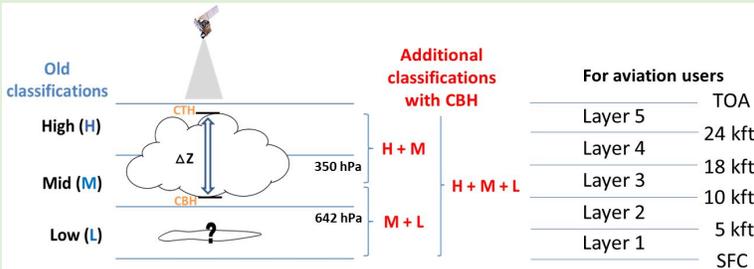
How is the product created?

The product is generated by extracting information from several data sources, which are combined and displayed along flight routes with a 1000 ft vertical resolution. The product incorporates CTH data (derived from infrared observations) along with an estimate of CBH, and is categorized by cloud top phase (also from infrared observations). Cloud top phase retrievals are combined with temperature (derived from satellite data called **NUCAPS** or from the GFS numerical weather prediction model) to determine cloud phase below the cloud top (e.g., “possibly mixed”). Cloud bases (CBH) are estimated with input from cloud tops (CTH) and cloud water data from a statistical approach based on satellite radar and lidar sensors. When satellite input data is not available, GFS numerical weather model data is used as supplementary input. This process has been applied to NOAA polar orbiting satellites (**JPSS VIIRS**) for Alaska, and **GOES** geostationary satellite data was added for CONUS.

Impact on Operations

Applications:

Aviation: Vertical cloud structures from satellite data (applicable to both polar and geostationary sensors) provide information for aviation weather applications in combination with numerical weather models. Users can infer areas of potential icing and turbulence as well as smoke over the U.S.



3D cloud product improvement: CTH and CBH information is used to compute the cross section and Cloud Cover Layers (CCL) products. CBH introduces additional cloud coverage at lower levels, typically hidden under cloud top.

Limitations

Dependency on cloud optical properties:

The cross-section product relies on inputs from both cloud top and base products. CBH performance is highly dependent on the accuracy of cloud top and water path data. Regions designated as “missing” indicate suitable data is not available.

Multi-layer clouds: Determining the cloud base from satellites is still challenging due to inherent limitations of passive sensors. The algorithm is optimal for single layer clouds such as boundary layer clouds, thin cirrus clouds, and deep convection cells. This may limit the accuracy of the product for satellite observations consisting of multiple cloud layers.

Nighttime observations:

Nighttime performance may be degraded due to missing low cloud layers and difficulty in determining cloud water path at night. CVC should be used with caution at night.



